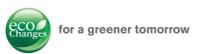
Global Partner, Local Friend.





FACTORY AUTOMATION

MITSUBISHI ELECTRIC **COLLABORATIVE ROBOT MELFA ASSISTA**





MELFA







MITSUBISHI ELECTRIC CORPORATION HEAD OFFICE: TOKYO BLDG., 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN

Printed July 2020

Specifications are subject to change without notice. All trademarks acknowledged.

GLOBAL IMPACT OF MITSUBISHI ELECTRIC







Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following:

Energy and Electric Systems

A wide range of power and electrical products from generators to large-scale displays.

Electronic Devices

A wide portfolio of cutting-edge semiconductor devices for systems and products.

Home Appliance

Dependable consumer products like air conditioners and home entertainment systems.

Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

Industrial Automation Systems

Maximizing productivity and efficiency with cutting-edge automation technology.

The new future of automation made possible by next-generation intelligent robots and e-F@ctory

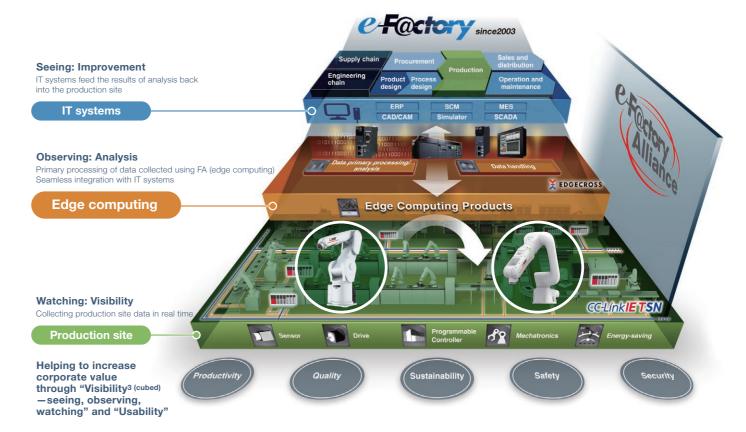


Providing improvements in productivity, quality, environmental protection, safety and security to help reduce companies' TCO* and boost their corporate value

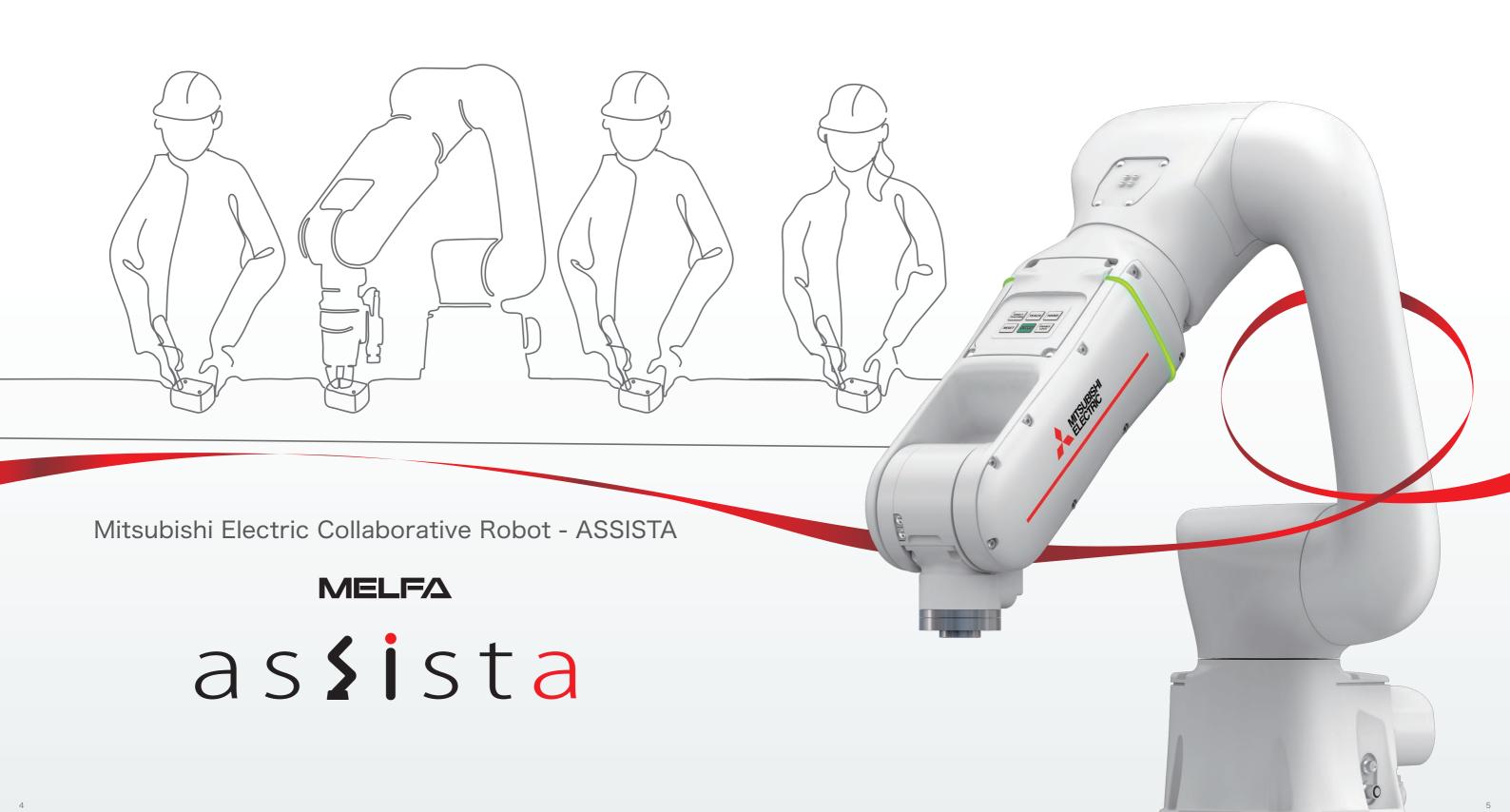
We offer solutions that use FA technology and IT to reduce total costs in everything from development through to production and maintenance, supporting customers to continuously improve their business operations and achieve truly cutting-edge manufacturing.

*TCO: Total Cost of Ownership

e-F@ctory is Mitsubishi Electric's trademark and registrated trademark.



Integrate. Collaborate.





MITSUBISHI ELECTRIC

0

0

No robot programming expertise required. Easy Programming MELFA as**\i**sta

Mitsubishi Electric Collaborative Robot - MELFA ASSISTA

Simpler, Easier and more flexible.

can share a workspace with humans.

0

0

This robot will change your perception of what a "ROBOT" is.

Easy operation with the Operation button.

Easy Control

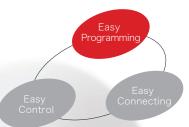
Easy connectivity with a wide variety of components.

Easy Connecting

0



Easy Programming



No Expertise for Robot Required.

You can create programs visually using intuitive operations with RT-Visual-Box. "Visual Programming"

- This software allows operators to simply program this robot with a "train by demonstration" programming interface. This allows them to move the robot arm position and set way-points easily.





AMR: Autonomous Mobile Robot



Simply Connect Grippers to Robot Arm
The ASSISTA Set-up wizard provides operators
with an easier more intuitive methodology for
gripper configurations.

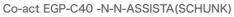






RT Visual Box (Engineering Software) lets operators set up grippers intuitively and easily.





Electric-powered Gripper

Weight: 885g (incl. attachments, fingers)
Grip Force: 35N (min)/140N (max) (4 levels)
Stroke: 6x2mm



HRC-03-099455 (Zimmer/Nabeya Bi-Tech Kaisha)

Electric-powered Gripper

Weight: Grip Force: 916g (incl. attachments, fingers) 50N (min)/190N (max) (4 levels, adjustable to 140N)

ke: 10×2n



ROB-SET ECBPM ASSISTA(SCHMALZ)

Electric-powered Adsorption Gripper

Weight: 631g (incl. attachments, adhesive pads)
Vacuum Pressure: -60kPa, Flow rate: 1.6L/min



KIT-ASSISTA-G (GIMATIC)

Electric-powered Gripper (Gripper parts be prepared separately.)

Weight: Grip Force: Stroke: 922g (incl. attachments) 98N 17.5×2mm

 $^{^{*}}$ These products may not be available in the region where you consider purchase. For details, please inquire at each company.

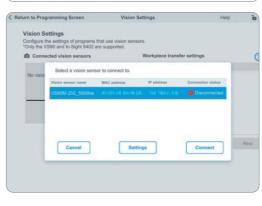


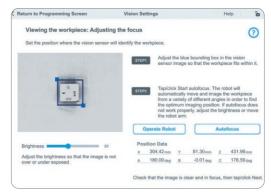
ASSISTA and the camera capture the target using the "RT VisualBox" auto-focus function.



"RT VisualBox" proprietary engineering tool

The vision camera focus adjustment and work registration can be configured simply by touching the screen. This means that you can use it even without special robot knowledge.







Vision Sensor In-Sight

The high-performance camera identifies the target and fixes position at high speed. Its compact size makes it ideal for attaching to the ASSISTA robot hand. This wire-saving type is equipped with PoE.

Model Name	Manufacturer	Inquiries, (as of April 2020)	Comments
In-Sight 8402M-363-50	COGNEX	COGNEX	
In-Sight 8402M-373-50	COGNEX	COGNEX	Supports PatMax RedLine® PatMax RedLine® cannot be used in combination with RT VisualBox



You can freely move ASSISTA

wherever needed whenever necessary.

The "AGV/AMR" unmanned transport cart secures the safety of various sensors and coexists with the operator. The company also provides a cart exclusively for use with ASSISTA, thereby enabling flexible response to changes in factory layout or the location where it is used.







WYN700-MR-ASSISTA (Tanabe Engineering Corporation)

W558 x D688 x H1000

(including bumper) *Reference values for AGV unit excluding robot

Weight Approx. 260kg

*Reference values for AGV unit excluding robot

HC-1-ASSISTA

(Satori Electric Co., Ltd.)

Size W600×D780×H910mm Weight Approx. 240kg

AK-R-ASSISTA (NIC Autotec, Inc.)

Size W600×D900×H900mm Weight Approx. 95kg

List of Collaborative Robot Partners

Gripper



SCHUNK Intec. K.K.

Schunk offers the most extensive lineup of compact grippers and all-purpose grippers in the industry, and has full range of accessories for the perfect match between arms and tools, thereby enabling it to support the most diversified of needs.

Minami-Shinagawa JN Bldg. 1F, 2-2-13, Minami-Shinagawa, Shinagawa-ku, Tokyo, 140-0004, Japan Intl: +81-3-6451-4321/Fax: +81-3-6451-4327 e-Mail:info@schunkjapan.jp

SCHUNK GmbH & Co. KG

Bahnhofstraße 106-134, D-74348 Lauffen/Neckar, Germany

e-Mail:info@de.schunk.com

SCHUNK Intec Precision Machinery Trading (Shanghai) Co., Ltd. Xinzhuang Industrial Park,

1F Building 1, No. 420 Chundong Road, Minhang District Shanghai 201108 Tel. +86-21-54420007 e-Mail:info@cn.schunk.com

SCHUNK Intec Inc

211 Kitty Hawk Drive Morrisville, NC 27560 Tel. +1-919-572-2705

e-Mail:info@us.schunk.com

This two-clawed parallel electric gripper is manufactured exclusively for collaborative robots, and compliant with safety standard ISO/TS 15066. Its LED status display enables simple status monitoring in the field. The durable design includes 4-stage grip force adjustment.



Model Co-act EGP-C40 N-N-Assista

Weight 885g (including attachments and fingers) Stroke 12mm (Single-claw stroke 6mm x 2)

Grip Force 35N, 70N, 105N, 140N (adjustable within 4 stages)



ZIMMER / Nabeya Bi-tech Kaisha

As an authorized distributor for Zimmer products in Japan, it offers a vast lineup of air grippers/electric grippers with high grip force (maximum 1800N)

1-banchi, Toukoudaich, Seki-shi, Gifu Prefecture, 501-3939, Japan Intl: +81-5-7523-1162/Fax: +81-5-7523-1719 e-Mail:info@nbk1560.com

Zimmer Group

Im Salmenkopf 5 77866 Rheinau - German +49 78 44 9139-0 e-Mail:info@zimmer-group.de

ZIMMER GROUP CHINA LTD

Level 2-D3, Bldg 4, 526, Fu-Te East 3rd Rd. CN 200131 Pudong, Shanghai

T +86 2161 630506

e-Mail:info.cn@zimmer-group.com

ZIMMER GROUP US INC. 1095 6th Street Ct SE US 28602 Hickory NC T +1 828 855 9722

e-Mail:info.us@zimmer-group.com

This two-clawed parallel electric gripper is exclusively for collaborative robots and compliant with safety standard ISO/TS 15066. Its built-in controller and mechanical cell clock ensure that it will not drop workpieces it is holding even in the event of a power outage



Model HRC-03-099455

Weiaht 916a (including attachments and fingers)

Stroke 20mm (Single-claw stroke 10mm x 2)

Grip Force 50N, 90N, 140N, 190N (adjustable within 4 stages)

^{*} These products may not be available in the region where you consider purchase. For details, please inquire at each company.

Gripper

Gimatic Japan Ltd.

As a gripper manufacturer, Gimatic offers a broad lineup of air and electric grippers, and can support the design, manufacture, and assembly of end effectors based on injection molded part extraction.

Contact (Japan)

11F TOC Bldg., 7-22-17 Nishi-Gotanda, Shinagawa-Ku, Tokyo 141-0031, Japan

Intl: +81-3-6206-4235/Fax: +81-3-6800-2770

e-Mail:info.jp@gimatic.com

Gimatic Srl

Via Enzo Ferrari 2/4 25030 Roncadelle (Bs) Italy Tel: +39 030 2584655

e-Mail:info@gimatic.com

GIMATIC AUTOMATION ENGINEERING (CHANGSHU) CO., LTD ROOM 902, N. 333, SOUTHEAST AVENUE

CHANGSHU RC 215500 Phone: +86051252977396 e-Mail: info.cn@gimatic.com

Contact (North America)

GIMATIC USA - Ohio

28300 EUCLID AVE WICKLIFFE, OHIO USA 44092

Phone: +1 216 535 4811 Fax: +1 216 535 4833 e-Mail:sales@gimaticusa.com

This parallel open/close plug-and-play gripper has a

built-in driver. Maintenance is not required for 10 million

cycles. Its original mechanism means that it does not

consume power while the jaw is stopped, and it maintains

its gripped state even in case of a power outage.

Dedicated Model KIT-ASSISTA-G

This is the industry's most compact, lightweight electric

vacuum pump. It achieves vacuum transport without

using air or a hose. Its smart body also makes it perfect

922a (including attachments) 35mm (Single-claw stroke 17.5mm x 2) Stroke

Grip Force 98N

Model

Weiaht

SCHMALZ

Schmalz Inc.

Schmalz is a vacuum transport device manufacturer founded in 1910. From highly versatile suction-type robot hands to suction pads, and high-performance vacuum generators, the company provides customers with a wide range of products that meet the needs of each industry, as well as vacuum know-how cultivated on a global scale.

3001-7 Odanacho, Tsuzuki-ku, Yokohama-shi, Kanagawa 224-0027, Japan Intl: +81-45-565-5150/Fax: +81-45-565-5151

e-Mail:info@schmalz.co.jp Contact (Furone)

J. Schmalz GmbH

Johannes-Schmalz-Str.1 DE-72293 Glatten

Tel: +49 7443 2403-0

e-Mail:schmalz@schmalz.de

Schmalz (Shanghai) Co. Ltd.

No. 1 Chunquan Road, CN-201210 Pudong Shanghai China TEL: +86 21 5109 9933

Mail: schmalz@schmalz.net.cn

HP: http://www.schmalz.net.cn

Contact (North America)

Schmalz Inc.

5850 Oak Forest Drive, Raleigh, NC 27616 USA

TEL: +1 (919) 713-0880

Mail: schmalz@schmalz.us

HP: https://www.schmalz.com/en/

Based on the concept of "plug-and-play that can be used right away," it is equipped with an ISO9409-1-compliant robot brush and can be simply attached without requiring the manufacturing of attachments. Electrical cabling is connected

simply using one connector

and it can operate using just

ROB-SET ECBPM ASSISTA

Grip Force -60kPa (vacuum max. pressure)

580g (includes hand bracket)

Model

Weight

Flow volume 1.6L/min



SMC Corporation

SMC was founded in 1959 as a general manufacturer of pneumatic devices. It currently manufactures and sells automatic control equipment. Support is provided via 54 domestic sales branches and 560 sales branches in 83 countries and regions.

JMHZ2-16D-X7400B-ASSISTA Model

Weiaht 581 g (includes product attachment bolts and straight pins) Stroke 10mm (Single-claw stroke 5mm x 2) Grip Force

32.5N (at outer diameter grip/0.5MPa) 43.5N (at inner diameter grip/0.5MPa)

15F Akihabara UDX, 4-14-1 Soto-Kanda, Chiyoda-ku, Tokyo 101-0021, Japan Intl: +81-3-5207-8271/Fax: +81-3-5298-5361 e-Mail:yokota.akinori@smcjpn.co.jp

Gripper

Convum Mytoku Ltd.

Device that act as robot hands are available. The fully standardized CRK Series includes brush, arm, and suction pad. No design work is required and delivery can be completed in a short period of time. Please contact us to discuss our suction hands.

502, Meiekiminami Bldg. No. 2, 4-8-17 Meiekiminami, Nakamura-ku, Nagoya City, Aichi Prefecture, 450-0003,

Intl: +81-52-533-9120

e-Mail:yukinori-hibino@convum.co.jp

Regions supported: Japan, Europe, China, North America. ASEAN, other overseas locations



Capable of connecting to various types of robots from each company via a shared mount-type guick changer. Plans are to increase the quantity of products to 40 beginning in 2020.

45F Sunshine 60 Bldg., 3-1-1 Higashi-Ikebukuro, Toshima-ku Tokyo 170-6045, Japan Intl: +81-3-5957-3794

e-Mail:takashi.suzuki@onrobot.com

Regions supported: Japan, Europe, China, North America, ASEAN, other overseas locations

Finger

THK Intechs

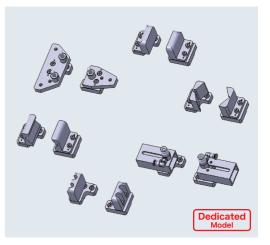
THK Intechs, through its experience with various types of collaborative robot engineering, has developed several convenient options for utilizing collaborative robots. Selecting these superior options will create unimaginable performance benefits. This will not only increase work efficiency, but also further increase the versatility of your collaborative robots.

N-HD-ASSISTA-NAIL-SET

Support hand GIMATIC "KIT-ASSISTA-G" proprietary

·Package containing eight types of pins/connectors that can be used to mount the GIMATIC "KIT-ASSISTA-G".

- ·Capable of supporting a variety of workpiece shapes by changing combinations
- ·Supports both grip and suction
- Secures mounting reproducibility via position-determining



2-12-10 Shibaura, Minato-Ku, Tokyo 108-0023, Japan Intl: +81-3-5730-3814 (direct line to Robot Dept.)/ FAX: +81-3-5730-3815 e-Mail:robot@thkintechs.co.jp

vasoiima

Yasojima Proceed Co., Ltd.

Proposes a robot hand that can fully utilize the characteristics of 3D printers.

Achieves consistency from design to manufacturing.

5F, IT Meieki Bldg., 3-11-22 Meieki, Nakamura-ku Nagoya City 450-0002, Japan Intl: +81-52-533-6130 e-Mail:usui@yasojima.co.jp Regions supported: Japan

Sensor

THK Intechs

THK Intechs, through its experience with various types of collaborative robot engineering, has developed several convenient options for utilizing collaborative robots. Selecting these superior options enables the realization of unimaginable performance benefits. This will not only increase work efficiency, but also further increase the versatility of your collaborative robots.

N-HD-SAF-ASSISTA-C Model Weight 987g (Hand not included) Compliance stroke 40mm Stroke

Portable mass Maximum 3Kg (weight of handss, fingers, etc.)

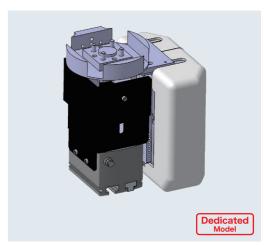
Contact (Japan)

2-12-10 Shibaura, Minato-Ku, Tokyo 108-0023, Japan Intl: +81-3-5730-3814 (direct line to Robot Dept.)/ FAX: +81-3-5730-3815

e-Mail:robot@thkintechs.co.jp

·By attaching this to a robot, it is possible to detect touch from the top and bottom clamping directions and mechanically protect robot and hand parts, peripheral devices, and body parts.

·Consideration is given to safety, with a built-in high-rigidity LM guide and SICK safety sensor.



20

Sensor



Since its foundation, IDEC has been engaged in manufacturing that prioritizes the safety of people and machinery, and focuses on reliability and ease of use. Even in environments where cooperation is required, we provide safety and security that goes that one step further.

2-6-64 Nishimiyahara, Yodogawa-ku, Osaka City 532-0004, Japan

Intl: +81-6-6398-2571

e-Mail:s.mitsugochi@jp.idec.com

Regions supported: Japan, Europe, China, North America, ASEAN, other overseas

locations

SICK JAPAN

Sensor Intelligence.

Providing solutions that enable collaborative robots to be used more efficiently.

- ① A safety laser scanner that can be used in a wide variety of environments 2 A safety controller that can be used intuitively with limited wiring
- 3 Safety services such as providing risk assessments and sample programs

13F, Harmony Tower, 1-32-2 Honmachi, Nakano-Ku. Tokvo 164-0012, Japan

Intl: +81-3-5309-2112

Regions supported: Japan, Europe, China, North America,

ASEAN, other overseas locations

Cable Guide

laus was founded in 1964, and its service network now extends to 72 countries throughout the world, including its head office in Germany. Based on its resin material development, molds, and molding technologies, with reliable technologies accumulated through experience, and achieving an impressive track record, the company strives to improve the mechanical performance and productivity of its customers throughout the world, doing so by aiming for plastics with longer service life (\uparrow extended lifetime with

Model Name TRE30-ASSISTA-S TRE30-ASSISTA-KL

15F, ARCA Centre, 1-2-1 Kinshicho, Sumida-ku, Tokyo 130-0013, Japan Intl: +81-3-5819-2500/Fax: +81-3-5819-2055

e-Mail:helpdesk@igus.co.ip

"Triflex R" multi-jointed cable protection tubes can be affixed on the robot arm section simply by hand, without requiring the use of any tools, enabling power to be provided smoothly to movable parts.

Type using wiring from the upper section of the arm (short type) ●TRE30-ASSISTA-S

TRF.30.050.0-75links TR.COB.01.30.Z1.0 1 item (surface fastener 1m) TR COR 01 30 70 0 1 item (surface fastener 1m)



Type using wiring from the base (long type)

●TRE30-ASSISTA-L TRE.30.050.0-150links TR.COB.01.30.Z1.0 1 item (surface fastener 1m)



murrplastik

KMECS Co., Ltd.

Murrplastik Head Office: Baden-Württemberg, Germany https://www.murrplastik.de/

This global company provides resilient cable protection and management systems, that can be mounted easily, such as cable drag chains, robot cable protective tubing, cable label rings, wire-saving cable entry systems, etc.

Model Name FHS-C-Set ASSISTA-RV5 FHS-UHE-Set ASSISTA-RV5

FHS-SH-Set AS

Contact (Japa

7F, Yoshiyasu Kanda Bldg., 2-1-15 Iwamotocho, Chiyoda-ku, Tokyo 101-0032, Japan Intl: +81-3-3864-0888/Fax: +81-3-3864-0881

e-Mail:s.masuda@kmecs.co.ip

This set protects the external cabling of collaborative robots.

It is also simple to mount the harnessed cables.



I Hand Cart

22

佐鳥電機株式会社 Satori Electric Co., Ltd.

A trading company for control/FA machinery. In addition to robot carts, automation and factory IoT solutions are offered. Please also inquire regarding interest in automating facilities.

HC-1-ASSISTA Model W600×D780×H910

Weight 240kg

1-14-10 Shiba, Minato-ku, Tokyo 105-0014, Japan Intl: +81-3-3452-7161/Fax: +81-3-3798-2475 e-Mail:zhk-fasolution-sales@satori.co.jp

Movement is simple owing to the compact, square form. This is a convenient cart exclusively for use with the MELFA ASSISTA, which enables affixing the foot pedal and immediate-



Hand Cart



NIC, Autotec, Inc.

This device manufacturer uses originally developed industrial aluminum structural materials. By being the first in the world to create a numerical basis for frame rigidity values, aluminum robot frames have been standardized. Based on abundant performance data focusing on robot frames, the company proposes ideal frames to meet customers' needs.

AK-R-ASSISTA Size W600×D900×H900

Weight 95kg

11F, B Block, Ariake Frontier Bldg., 3-7-26 Ariake, Koto-ku, Tokyo 135-0063, Japan Intl: +81-3-5530-8060/Fax: +81-3-5530-8070

e-Mail:tokyo@nic-inc.co.jp

This is a dedicated ASSISTA frame for connecting controllers only and equipped with standard 24VDC power. In addition to the controller, it is possible to install peripheral devices and PLC units within the frame.



AGV/AMR



● 田辺工業株式会社

Tanabe Engineering Corporation

Single-handed support of all processes, from design to manufacturing, for various automated machinery. Capable of proposing peripheral equipment based on AGV customization where necessary

WYN700-MR-ASSISTA

Size W558 x D688 x H1000 (including bumper)

*Reference values for AGV main body excluding robot Weight Approx. 260kg

*Reference values for AGV main body excluding robot

7F, Koshin Bldg., 1-10 Kandaogawamachi, Chiyoda-ku, Tokyo 101-0052, Japan Intl: +81-3-5207-7140

e-Mail: webothers@tanabe-ind.co.jp

Utilizing guideless travel with a range sensor (laser range) guide laying construction is completely unnecessary on deployment. Additionally, not only the AGV main body, but also the safety sensors for robots, etc. can be customized to match a user's safety standards.



Software

Ricoh Industry Company, Ltd.

Utilizing its multi-view camera, this tool can be easily configured whenever, wherever necessary. It supports increasing production by enabling the simple checking of events such as the cause of equipment stoppage and tact fluctuation.

Captain Building, 4-8-8 Funabori, Edogawa-Ku, Tokyo 134-0091, Japan

1005 Shimogino, Atsugi, Kanagawa Prefecture, 243-0298, Japan https://industry.ricoh.com/alr/

Intl: +81-3-5674-1611

All Line Recognizer

Safety Fance



CAPTAIN Captain Industries, Inc.

Owing to the simple modular format, assembly of this safety fence is both quick and safe. Using only the dedicated X-KEY, the lightweight, easy-to-handle nature of the panel enables it to be assembled by one person.

Regions supported: Japan, Europe

Screw

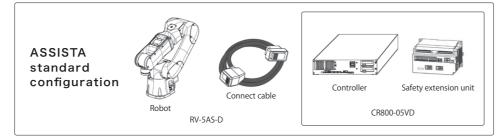


HIOS Inc.

This ultralightweight, compact electric driver can be attached to a robot using only two screws when integrated with HIOS' PAT. screws (TOTUPLA screw/INTRTORQUE), thereby fully supporting the deployment of automation.

1-35-1 Oshiage, Sumida-ku, Tokyo 131-0045, Japan Intl: +81-3-6661-8777/Fax: +81-3-6657-0888 e-Mail:ip hp@hios.com Regions supported: Japan

Robot arm



Standard specifications of RV-5AS-D robot

	Item	Unit	Specifications	
IP Rate			IP54	
Degree of freedom			6	
Installation posture			Floor mounted / ceiling mounted	
Structure			Vertical, multiple-joint type	
	Waist (J1)		±240	
	Shoulder (J2)		±148	
Operating	Elbow (J3)		±150	
range	Wrist twist (J4)	Degree	±200	
	Wrist pitch (J5)		±120	
	Wrist roll (J6)		±200	
	Waist (J1)		124 (59.6)	
	Shoulder (J2)		124 (34.0)	
Speed of	Elbow (J3)	D ,	124 (34.0)	
motion Note1)	Wrist twist (J4)	Degree/s	297 (142)	
	Wrist pitch (J5)		356 (215)	
	Wrist roll (J6)		360	
Maximum reach radi	ius	mm	910	
Maximum	High-speed operation mode		1,000	
resultant	Collaborative operation mode (Standard operation)	mm/sec	250	
velocity Note2)	Collaborative operation mode (Low-speed operation)		50	
Land	Rating	l.a	5	
Load	Maximum Note3)	kg	5.5	
Pose repeatability		mm	±0.03	
Ambient temperatur	re Note4)	℃	0 to 40	
Mass		kg	32	
Wiring	Hand I/O	-	Mechanical interface: 2 inputs/4 outputs Forearm: 6 inputs/0 outputs Base: 0 inputs/4 outputs	
	Force sensor cable/Spare cable	-	5-conductor (24 V/0.7 A) One of the conductors should be used for the frame ground (FG).	
	LAN cable	-	Cat-5e supported	
SI 1.	Primary hoses	-	Φ6×2	
Plumbing	Secondary hoses	-	Φ 4 $ imes$ 4 From the base of the robot to the elbow.	
Supply pressure		MPa	0.54	

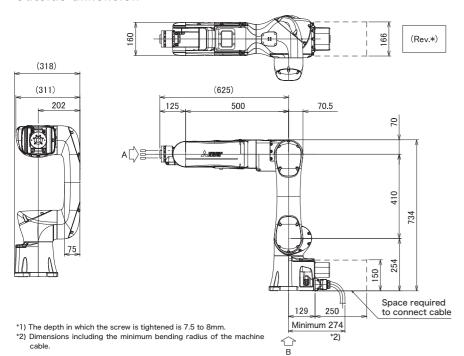
Note1) Values in parentheses indicate the maximum speed when the input voltage is single-phase 100 to 120 VAC.

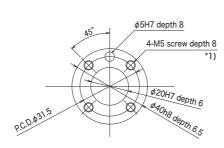
Note2) These values represent the maximum overall speed of all axes combined. The safety functions limit the robot to the speeds shown in the table. For accurate collision force data when the robot is in Collaborative operation mode, measure collision forces under actual operating conditions.

Note3) Allowable load when the mechanical interface faces downward at an inclination within ±10° to the vertical direction.

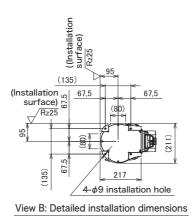
Note4) Sets the robot's operating environmental temperature as parameter OLTMX. The initial value is 30 (°C). Corresponding to the environment, the continuous control action performance and the overload-protection function are optimized.

Outside dimension





View A: Detail of mechanical interface



CR800-05VD controller specifications of controller

	J-05VD cont			
	Item	Unit	Specification	Remarks
Number o	of control axis	-	Simultaneously 6	-
Memory capacity	Programmed positions	point	39,000	Number of program blocks when using RT VisualBox: 2000 (vision sensor not
	No. of steps	step	78,000	used), 1800 (vision sensor used) Number of programs: 505 (vision sensor not
	Number of program	-	512	used), less than 500 (vision sensor used) Note1)
Robot lan	guage	-	MELFA-BASIC VI	-
Teaching	method	-	Pose teaching method, MDI method	-
	Input/output	point	0/0	Max. 64/64 by option
	Dedicated input/output	-	Assigned with general-purpose input/output	The signal number of "STOP" input signals is fixing.
External	Emergency stop input Note2)	point	1 (duplicated)	
input and	Emergency stop output	point	1 (duplicated)	
output	Mode selector switch input Note3)	point	1 (duplicated)	
	Mode output	point	1 (duplicated)	
	Robot error output	point	1 (duplicated)	
	Door switch input	point	1 (duplicated)	
	Encoder input	Channel	2	-
Safety I/O		point	8 (duplicated) / 4 (duplicated)	Safety extension unit
	Force sensor interface	Channel	1	-
	Remote input/output	Channel	1	For connection to the Safety extension unit.
	USB	port	1	Ver. 2.0 HighSpeed device functions only. USB mini-B
Interface	Ethernet	port	1	For customer: 1000BASE-T/ 100BASE-TX/10BASE-T
	Luieniet		1	Dedicated T/B port: 100BASE-TX/10BASE-T
	Option slot	slot	2	For option interface
	SD memory card slot	slot	1	For extended memory
	RS-422	port	1	Dedicated T/B port
Power	Input voltage rang	V	Single phase AC 100 to 120 Single phase AC 200 to 230	The rate of power-supply voltage fluctuation is within 10%.
source	Power capacity	kVA	1.0	Does not include rush current. Note4)
	Power supply frequency	Hz	50/60	-
Outline dimensions		mm	430(W) x 425(D) x 99.5(H)	Excluding protrusions
Mass		kg	Approx.12.5	-
IP Rate			IP20	
Ambient	temperature	°C	0 to 40	Without freeze
Ambient humidity		%RH	45 to 85	Without dew drops
Ambient	numidity	%0KH		Without dew drops

Note1) The maximum number of usable programs differs depending on the number of types of workpieces that are registered.

Note2) Only the STO function can meet the requirements of Category 4, Performance Level e. At factory settings, the STO function meets the requirements of Category 3, Performance Level d. To make the STO function meet the requirements of Category 4, Performance Level e, change the parameter setting.

Note3) Provide a mode selector switch to change the mode (MANUAL/AUTOMATIC) of the controller.

Note4) The prover capacity is the recommended value. The power capacity does not

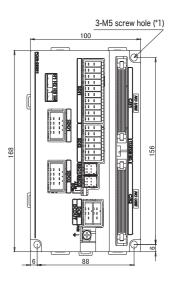
the Controller.

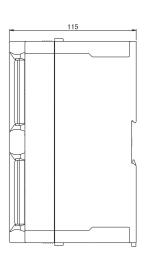
Note4) The power capacity is the recommended value. The power capacity does not include the rush current when the power is turned ON. The power capacity is a guideline and the actual operation is affected by the input power voltage.

Note5) The robot must be grounded by the customer.

Safety extension unit

Item			Description	Remarks	
	STO function		The function electrically shuts off the driving energy to the motor of the robot arm.	IEC 60204-1 Corresponds to stop category 0	
Safety function	SS1 function		The function to control and decelerate the motor speeds of the robot. After stopping, the robot transitions to the STO state.	IEC 60204-1 Corresponds to stop category 1	
	SS2 funct	ion	The function to control and decelerate the motor speeds of the robot. After stopping, the robot transitions to the SOS state.	IEC 60204-1 Corresponds to stop category 2	
	SOS function		Without shutting off the driving energy to the motors, this function monitors the robot so that it stays at rest.		
	SLS funct	ion	This is a function to monitor each part of the robot arm so that their speeds do not exceed monitoring speeds.	When SOS, SLS, SLP, and STR detect error, activate SS1. EN 61800-5-2 compliant	
	SLP funct	ion	The function monitors specified monitoring positions so that they do not go across position monitoring planes.		
	STR function		This function ensures that the torque limits of each motor in the robot are not exceeded.		
Safety	Standard		EN ISO 10218-1: 2011 ISO/TS 15066: 2016 EN ISO 13849-1: 2015 IEC 61800-5-1: 2007 EN 61800-5-2: 2017 EN 61800-6-7: 2015 EN 61326-3-1: 2017 IEC 61508-1: 2010 IEC 61508-3: 2010 IEC 61508-3: 2010 EN 62061: 2005/A2: 2015 IEC 62061: 2005/AUD1: 2012/AMD2: 2015	-	
performance	Performance	STO	SIL2, PLd/Category 3 (at factory settings) SIL3, PLe/Category 4 (with changes to parameters)	-	
		SS1,SOS,SS2, SLS,SLP, STR	SIL 2, PLd/Category 3	-	
		STO	PFH = 1.40×10 ⁻⁸ [1/h]	-	
	Dangerous failure rate	SS1,SS2,SOS	$PFH = 3.42 \times 10^{-7} [1/h]$	-	
		SLS	$PFH = 3.42 \times 10^{-7} [1/h]$	-	
		SLP	$PFH = 3.42 \times 10^{-7} [1/h]$	-	
		STR	$PFH = 3.62 \times 10^{-7} [1/h]$	-	
	Power supply	Voltage	24 V DC±5% Ripple 0.2 V (P-P)	Supplied by customer	
Safety extension unit	specifications	Maximum consumption current	300 mA	-	
	IP Rate		IP20	-	
	Weight		0.8kg	It must be kept away from heat	
	Environment	Operating temperature range	0 to 40°C	appliances and other heat sources	
	Relative humid		45 to 75%	Without drew drop	
	Input signal		8 routes (duplicated signal)		
	Output signal		4 routes (duplicated signal)		





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The list of robot option equipment

Item	Туре	Description	
Machine cable (replacement)	1F-□□UCBL-41	" " in type shows the length of the cables as follows. 02=2 m, 10=10 m (Changed from the original length of 5 m)	
Solenoid valve set	1F-VD0□-01(Sink)	Sets with one or two valves are available. $\Phi 4$ diameter output hoses The number that replace	
Soletioid valve set	1F-VD0□E-01(Source)	" " indicates the number of valves the solenoid has (1 or 2).	
2-piece force sensor conversion cable set	1F-ASSISTA-ADCBL	2-piece force sensor conversion cable set (hand cable/base cable) required to connect the force sensor to the robot.	
Vision sensor mounting bracket	1F-ASSISTA-2DVSFLG	Bracket required to connect a vision sensor to the hand.	

The list of the controller option equipment and special specification

Item	Туре	Description	
Easy-setup kit	4F-ASSISTASETUP-JP (for Europe/China)	A kit which aids setup that consists of switches,	
,	4F-ASSISTASETUP-EU (for Japan/NorthAmerica)	a connector cable, and a 24 V power supply.	
RT VisualBox	3G-30C-WINE	Windows 10 Supporting English.	
RT ToolBox3	3F-14C-WINE	Windows 7, Windows 8, Windows 8.1, Windows 10 Supporting English. (With the simulation function) Ver.1.70Y or later	
RT ToolBox3 mini	3F-15C-WINE	Windows 7, Windows 8, Windows 8.1, Windows 10 Supporting English. Ver.1.70Y or later	
Simple teaching pendant	R32TB/R32TB-15	Cable length 7m, Cable length 15m	
Highly efficient teaching pendant	R56TB/R56TB-15	Cable length 7m, Cable length 15m	
Parallel I/O Interface	2D-TZ368(Sink type)	DO: 32 point	
r didilei i/O liiteriace	2D-TZ378(Source type)	DI: 32 point	
External I/O cable (For Parallel I/O Interface)	2D-CBL05	CBL05:5m, CBL15:15m Use to connect the external peripheral device to the parallel input/output interface.	
CC-Link interface *1	2D-TZ576	Only intelligent device station, Local station.	
Network base card *1 (EtherNet/IP interface)	2D-TZ535	Communication interface for mounting the Anybus CompactCom module manufactured by HMS. The customer needs to prepare the EtherNet/IP module (AB6314) manufactured by HMS.	
Network base card *1 (PROFINET interface)	2D-TZ535-PN	Communication interface for mounting the Anybus CompactCom module manufactured by HMS. The customer needs to prepare the PROFINET IO module (AB6489-B) manufactured by HMS.	
Network base card *1 (CC-Link IE Field interface)	2F-DQ535	Communication interface for mounting the Anybus CompactCom module manufactured by HMS. The customer needs to prepare the CC-Link IE Field module (AB6709) manufactured by HMS.	
Network base card *1 (EtherCAT interface)	2F-DQ535-EC	Communication interface for mounting the Anybus CompactCom module manufactured by HMS. The customer needs to prepare the EtherCAT module (AB6607) manufactured by HMS.	
SD memory card *1	2F-2GBSD	Memory card capacity 2GB.	

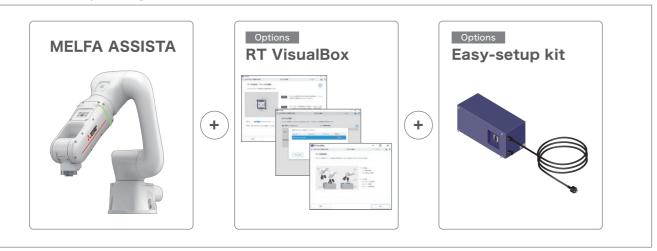
^{*1} Not supported by RT VisualBox.

The list of function extension device

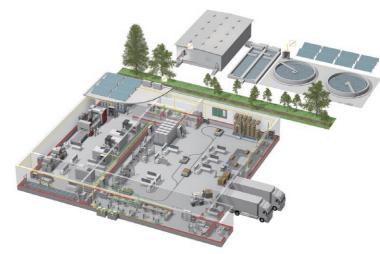
Item	Type name	Specifications
Force sensor set *1	4F-FS002H-W200	A set of devices necessary for force sense control function, such as a force sensor, an interface unit, and support software.

^{*1} Not supported by RT VisualBox.

ASSISTA Startup Configuration



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^{*} Not all products are available in all countries.